

IN THE CLAIMS:

1-18. (Cancelled).

Please add the following new claims:

19. (Currently Amended) A method of aligning a first tubular with a second tubular, comprising:
- providing a remotely controllable positioning head;
 - determining a position of the head, wherein the position of the head ~~aligns~~ would align the first tubular with the second tubular;
 - memorizing the position of the head; and
 - positioning the first tubular at the memorized position.
20. (Previously Presented) The method of claim 19, wherein a third tubular is positioned by recalling the memorized position.
21. (Previously Presented) The method of claim 19, wherein one or more sensing devices are used to determine the position of the head.
22. (Previously Presented) The method of claim 21, wherein each of the one or more sensing devices comprises a linear transducer.
23. (Previously Presented) The method of claim 19, wherein a telescopic arm is used to position the head.
24. (Previously Presented) The method of claim 23, wherein a piston and cylinder assembly is used to extend or retract the telescopic arm.

25. (Previously Presented) The method of claim 24, wherein a sensing device is used to determine the amount of extension or retraction of the piston and cylinder assembly.
26. (Previously Presented) The method of claim 19, wherein the position of the head is memorized electronically.
27. (Previously Presented) The method of claim 19, wherein the position of the head is memorized mechanically.
28. (Previously Presented) The method of claim 19, wherein the position of the head is memorized optically.
29. (Currently Amended) A method for aligning a first tubular with a second tubular, comprising:
 securing the first tubular in a gripping member;
 aligning the second tubular with the first tubular using a remotely actuatable apparatus;
 memorizing the position of the remotely actuatable apparatus when the second tubular is aligned with the first ~~tubular~~ tubular;
 connecting the second tubular to the first tubular; and
 releasing the first ~~tubular~~ tubular from the gripping member.
30. (Currently Amended) The method of claim 29, further comprising:
 lowering the first tubular and the second tubular;
 securing the second tubular in the gripping member;
 gripping a third tubular to be connected to the second tubular using the remotely ~~controllable~~ actuatable apparatus;
 moving the remotely actuatable apparatus to position the third tubular at the memorized position; and
 connecting the third tubular to the second tubular.

31. (Previously Presented) The method of claim 30, further comprising adjusting the position of the third tubular before connecting to the second tubular.

Please add the following new claims:

32. (New) The method of claim 19, further comprising adjusting the position of the head.

33. (New) The method of claim 32, further comprising memorizing the new position of the head.

34. (New) The method of claim 29, wherein connecting the second tubular to the first tubular is performed before memorizing the position of the remotely actuatable apparatus.

35. (New) The method of claim 34, wherein memorizing the position is performed when the second tubular is partially connected to the first tubular.

36. (New) A method of running tubulars into a wellbore, comprising:
providing a tubular string suspended in the wellbore;
positioning a tubular in a memorized location over the tubular string;
connecting the tubular to the tubular string, thereby forming an extended tubular string; and
lowering the extended tubular string into the wellbore.

37. (New) The method of claim 36, wherein the memorized location is memorized electronically.

38. (New) The method of claim 36, wherein the memorized location is memorized mechanically.

39. (New) The method of claim 36, wherein the memorized location is memorized optically.